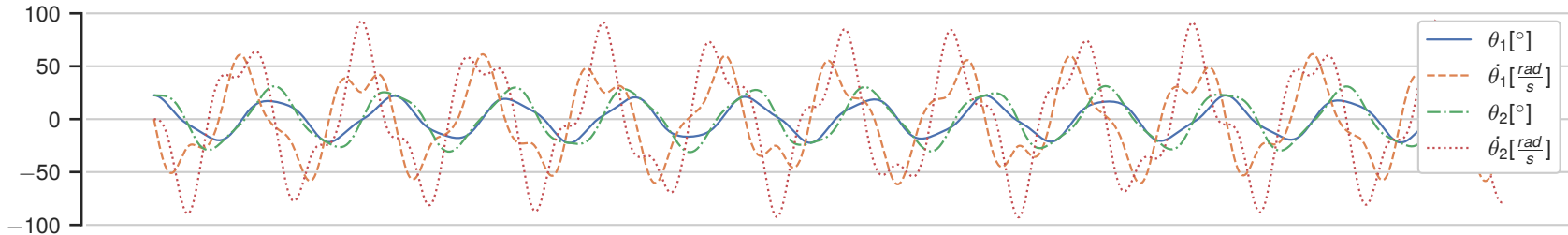


# Double Pendulum with different Inertias

Mass = 1, Inertia = 0



Mass = 1

