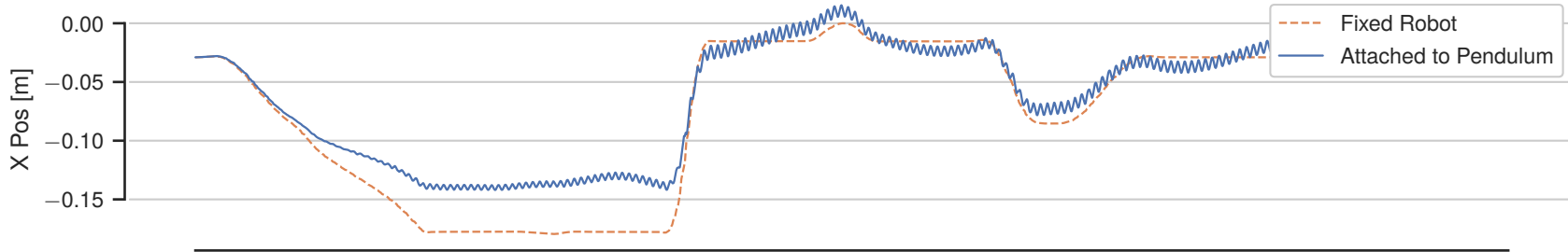


Without Compensation



With CMGs informed by robot model

